## K. S. R. COLLEGE OF ENGINEERING, TIRUCHENGODE - 637 215 DEPARTMENT OF MATHEMATICS 18MA343 - NUMERICAL COMPUTATIONAL TECNIQUES MULTIPLE CHOICE QUESTIONS

- 1. Every polynomial equation of the nth degree has \_\_\_\_\_\_ roots.
  - A. n
  - B. n+1
  - C. n+2
  - D. n-1
  - ANSWER: A

2. If f(x) =0 has a root between a & b then f(a) & f(b) are of \_\_\_\_\_\_ signs.

- A. opposite
- B. same
- C. negative
- D. positive
- ANSWER: A

3. If two of the roots are 1-i & 2, then the 3rd degree equation is \_\_\_\_\_\_.A. x3 -21x2 +6x -4=0.

- B. x3-4 x2+6x +4=0 C. x3-4 x2+6x -4=0 D. x3+4x2+6x -4=0 ANSWER: C
- 4. Which method gives a unique set of values to the constants in the equation of the fittingcurves?
  - A. Horners method
  - B. Method of least squares
  - C. Interpolation
  - D. Newton's Method

## ANSWER: B

- 5. A polynomial of the form y=ax2+bx+c is called \_\_\_\_\_\_.
  - A. linear equation
  - B. Second degree equation
  - C. reciprocal equation
  - D. bi quadratic equation
  - ANSWER: B
- 6. The line obtained by the method of least square is known as the line of \_\_\_\_\_\_.
  - A. straight line
  - B. second degree equation
  - C. best fit
  - D. polynomial equation

ANSWER: C

- 7. The sum of deviation of the actual values of Y and the computed values of Y is\_\_\_\_\_.
  - A. 0
  - B. 1
  - C. Maximum
  - D. MinimumANSWER: A

8. In the function y = f(x), the independent variable x is called \_\_\_\_\_\_.

- A. entry
- B. argument
- C. intermediate
- D. interpolation

ANSWER: B

9. The relationship between E and delta is \_\_\_\_\_.

- A. E =1-delta
- B. E =1+delta
- C. E = delta 1
- D. E = delta
- ANSWER: B

10. The relationship between E and small delta is \_\_\_\_\_\_.

- A. small delta = 1-E
- B. small delta = E-1
- C. small delta = (E-1)-1
- D. small delta =  $E^{(1/2)}-E^{(-1/2)}$
- ANSWER: D
- 11. Choose the correct one.
  - A. E = ehD = 1-delta
  - B. E = ehD = 1 + delta
  - C. E = e-hD = 1+delta
  - D. E = 1/ehD = 1/1+deltaANSWER: B

12. In the function y = f(x), the dependent variable y is called \_\_\_\_\_.

- A. entry
- B. argument
- C. intermediate
- D. interpolation

ANSWER: A

- 13. Iteration method is a \_\_\_\_\_ method
  - A. direct
  - B. indirect
  - C. self correcting
  - D. step by step

ANSWER: C

14. Gauss Elimination Method & Gauss Jordan Methods are \_\_\_\_\_\_ methods.

- A. direct
- B. indirect

C. self correcting

D. step by step

ANSWER: A

15. The rate of convergence of Gauss Seidel Method is \_\_\_\_\_\_ that of Gauss JacobiMethod.

- A. once
- B. twice
- C. thrice
- D. reciprocal

ANSWER: B

16. \_\_\_\_\_ method is very fast compared to other methods.

- A. Gauss Elimination
- B. Gauss Jordan
- C. Gauss Seidel
- D. Gauss Jacobi

ANSWER: C

17. The order of convergence of Regula-Falsi method is \_\_\_\_\_\_.

- A. 2
- B. 1.172
- C. 1.618
- D. 1.17
- ANSWER: C

18. The Newton Raphson Method is also called \_\_\_\_\_\_.

- A. Bolzano's Bisection Method
- B. Iterative Method
- C. Method of Tangents
- D. Newton's MethodANSWER: C

19. The order of Newton Raphson Method is \_\_\_\_\_\_.

- A. 1
- B. 2
- C. 3
- D. 4

ANSWER: B

20. The modification of Gauss Elimination Method is \_\_\_\_\_\_.

- A. Gauss Jordan Method
- B. Gauss Jacobi Method
- C. Gauss Elimination Method
- D. Gauss Seidel Method

ANSWER: A

21. If alpha,beta,gamma are the roots of the equation x3-14x+8=0,then product of the roots

- is\_\_\_\_\_.
- A. -8
- **B.** -18
- C. 28

D. 38 ANSWER: C

- 22. \_\_\_\_\_\_ method is used for finding the dominant Eigen-value of a matrix.
  - A. Gauss Elimination Method
  - B. Gauss Jordan Method
  - C. Newton Raphson Method
  - D. Power methodANSWER: D

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23. Euler corrector is _____.
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- A. Yn+1 = Yn + hYn.
- B. Y n+1 = Yn+h/2(Yn + Y n+1)
- C. Y n+1 = Yn + h/2(Y'n+Y' n+1)
- D. Y n+1 = Yn' hYn'

ANSWER: D

24. Let f is \_\_\_\_\_\_ on (a, b) and f(a)<f(b). Then bisection method generates a sequence {Pn} approximating a zero p of f with |Pn-P|less than or equal to(b-a)/2n,n greater than or equal to1.

- A. continuous function
- B. discontinuous function
- C. constant function
- D. multivariate function

ANSWER: A

- 25. In Euler's method: Given initial value problem y'=dy/dx=f(x, y) with y(x0) = y0, thenapproximation is given by\_\_\_\_\_.
  - A.  $y_n+1=y_n+hf(x_n-1, y_n-1)$
  - A.  $y_{1}+1-y_{1}+m(x_{1}-1, y_{1}-1)$ B.  $y_{1}+1=y_{1}+hf(x_{1}, y_{1}-1)$
  - C.  $y_n+1=y_n+hf(x_n-1, y_n)$
  - D.  $y_n+1=y_n+hf(x_n, y_n-1)$

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ANSWER: B
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26. y(x+h) = y(x) + h f(x,y) is referred as \_\_\_\_\_method.

- A. Euler
- B. Modified Euler
- C. Taylor's Series
- D. Runge-Kutta

ANSWER: A

27. When more than one value is involved then the problem is known as \_\_\_\_\_\_.A. initial Value Problem.

- B. boundary Value Problem
- C. interpolation
- D. extrapolation

ANSWER: B

28. The error in the trapezoidal rule is of the order\_\_\_\_\_.

- A. h
- B. h^ 2
- C. h ^ 3

D. h ^4 ANSWER: B

29. The error in the Simpson's rule is of the order\_\_\_\_\_.

A. h B. h ^ 2 C. h ^ 3 D. h ^ 4 ANSWER: D

30. Romberg's method is also known as\_\_\_\_\_.

- A. Trapezoidal ruleB. Simpson's (1/3)rd RuleC. Simpson's (3/8)th Rule
- D. Rombergs Integration

ANSWER: D

31. Simpson's 1/3rd rule of integration is exact for all polynomials of degree not exceeding

A. 1 B. 2 C. 3 D. 4 ANSWER: B

32. Simpson's 3/8th rule is applicable only when\_\_\_\_\_.

- A. n is a multiple of 3
- B. n is a multiple of 6
- C. n is a multiple of 8
- D. n is a multiple of 24

ANSWER: A

33. In Simpson's 1/3rd rule the number of intervals must be \_\_\_\_\_.

- A. a multiple of 3
- B. a multiple of 6
- $C. \ odd$
- D. even

ANSWER: D

- 34. The order of Euler method is \_\_\_\_\_\_.
  - A. h
  - B.  $h \wedge 2$
  - C. h ^3
  - D.  $h \wedge 4$

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ANSWER: B
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- 35. \_\_\_\_\_ method is used for finding the approximate solution either rational or irrationalof numerical equation.
  - A. Euler
  - B. Taylor

C. Horner's D. Modified Euler ANSWER: C

- 36. The two segment trapezoidal rule of integration is exact for integrating at most \_\_\_\_\_\_order polynomials.
  - A. first
  - B. second
  - C. third
  - D. fourth

ANSWER: A

37. The process of finding the equation of the curve of best fit, which may be most suitable forpredicting the unknown values, is known as\_\_\_\_\_.

- A. curve fitting
- B. theory of equations
- C. interpolation
- D. extrapolation

ANSWER: B

38. Newton-Raphson method is applicable to find the solution of \_\_\_\_\_.

- A. both algebraic and transcendental equations
- B. both algebraic and transcendental and also used when the roots are complex
- C. algebraic equations only
- D. transcendental equations only

ANSWER: A

- 39. \_\_\_\_\_ is used to denote the process of finding the values inside the interval(X0, Xn).
  - A. Interpolation
  - B. Extrapolation
  - C. Iterative
  - D. Polynomial equation

ANSWER: A

40. The forward difference operator is denoted by the symbol \_\_\_\_\_\_.

- A. delta
- B. omega
- C. nabla
- D. infinity

ANSWER: A

41. The backward difference operation is denoted by the symbol\_\_\_\_\_.

- A. nable
- B. delta
- C. omega
- D. infinity

ANSWER: A

- A. linear
- B. parabolic
- C. hyperbolic
- D. polynomial equation
- ANSWER: A

43. Lagrange's interpolation formula is used to compute the values for \_\_\_\_\_\_ intervals.

- A. equal
- B. unequal
- C. open
- D. closed
- ANSWER: B

44. Newton forward interpolation formula is used for \_\_\_\_\_\_ intervals.

- A. equal
- B. unequal
- C. open
- D. closed

ANSWER: A

45. Fourth degree equations are also called \_\_\_\_\_\_ equations.

- A. quadratic
- B. cubic
- C. linear
- D. bi-quadratic
- ANSWER: D
- 46. Let the arithmetic mean of two numbers be 9 and the geometric mean be 4, then thesenumbers are the roots of the quadratic equation\_\_\_\_\_.
  - A. x2 +18x +16=0
  - B. x2 -18x-16 =0
  - C. x2 +18x -16=0
  - D. x2-18x+16=0
- ANSWER: D

47. If (1-p) is a root of quadratic equation  $x^2 + px + (1-p) = 0$ , then its roots are\_\_\_\_.

- A. (0, 1)
- B. (-1, 2)
- C. (0, -1)
- D. (-1, 1)

ANSWER: C

- 48. If one root of the equation  $x^2 + px + 12 = 0$  is 4 and the equation  $x^2 + px + q = 0$  have equalroots, then the value of q is\_\_\_\_\_.
  - A. 49/4
  - B. 4
  - C. 3

D. 12

ANSWER: A

49. If the graph of the function y = f(x) is symmetrical about the line x = 2, then\_\_\_\_.

A. f(x+2)=f(x-2)

- B. f(2+x)=f(2-x)
- C. f(x) = f(-x)
- D. f(x) = -f(-x)
- ANSWER: B
- 50. If the system of linear equations x + 2ay + az = 0; x + 3by + bz = 0; x + 4cy + cz = 0 have anon-zero solution, then a, b, c\_\_\_\_\_.
  - A. are in Arithmetic Progression
  - B. are in Geometric Progression
  - C. are in Harmonic Progression
  - D. satisfy a+2b+3c=0

ANSWER: C

- 51. If the sum of the roots of the quadratic equation  $ax^2 + bx + c = 0$  is =the sum of the squares of their reciprocals, then a/c, b/a, and c/b are in\_\_\_\_\_.
  - A. are in Arithmetic Progression
  - B. are in Geometric Progression
  - C. are in Harmonic Progression
  - D. are in Arithmetic and Geometric Progression

ANSWER: C

- 52. In the function y = f(x) the dependent variable is \_\_\_\_\_.
  - A. y
  - B. x
  - C. f(x)
  - D. a constant
  - ANSWER: A
- 53. The first two terms of a GP add up to 12. The sum of the third and the fourth terms is 48. If the terms of the GP are alternately positive and negative, then the first term

is\_\_\_\_\_. A. -2

- B. -4
- C. -12
- D. 8

ANSWER: C

- 54. In the function y=f(x) the independent variable is \_\_\_\_\_.
  - A. y
  - B. x
  - C. f(x)
  - D. a constant
  - ANSWER: B
- 55. The translation operator is denoted by \_\_\_\_\_.
  - A. E
  - B. nabla
  - C. omega
  - D. T

ANSWER: A

56. If the roots of the equation x2-bx+c=0 are two consecutive integers, then b2-4ac =

A. 1 B. 2 C. 3 D. -2 ANSWER: A

57. A smooth curve that can be drawn to pass through near the plotted points is called

- A. curve fit
- B. approximating curve
- C. empirical curve
- D. linear curve

ANSWER: B

- 58. The equation of approximate curve taken as an approximate relation between x and y iscalled \_\_\_\_\_\_.
  - A. curve fit
  - B. approximating curve
  - C. empirical relation
  - D. linear form

ANSWER: C

- 59. The general problem of finding equations of approximating curves which fit a given data iscalled \_\_\_\_\_\_.
  - A. curve fitting
  - B. approximating curve
  - C. empirical relation
  - D. linear form

ANSWER: A

- 60. The best representative curve to the given set of points for which the sum of the squares of the residuals is a minimum is known as\_\_\_\_\_.
  - A. curve fitting
  - B. approximating curve
  - C. empirical relation
  - D. principles of least squares

ANSWER: D

- 61. The \_\_\_\_\_\_ matrix in the normal equations is symmetric.
  - A. square
  - B. scalar
  - C. co-efficient
  - D. upper triangular

ANSWER: C

62. If alpha,beta,gamma are the roots of x3 +px2 +qx+r = 0, then the values of sum of alpha=\_\_\_and sum of (alpha\*beta)=\_\_\_\_.

- A. -p and -q
- B. -p and q
- C. p and -q
- D. p and q
- ANSWER: B
- 63. If alpha,beta,gamma are the roots of the equation x4+px3 +qx2 +rx+s = 0, then the values ofsum of (alpha\*beta)=\_\_\_\_and sum of(alpha\*beta\*gamma)=\_\_\_\_.
  - A. -p and -q
  - B. q and -r
  - C. g and r
  - D. p and q
- ANSWER: B

64. If alpha, beta, gamma are the roots of x3+px+q=0, then the vale of sum of(1/alpha)=\_\_\_\_\_.

- A. p/q
- B. q\p
- C. -p/q
- D. p2/-q
- ANSWER: C

65. If alpha, beta, gamma are the roots of x3-3x+1=0, then the value (alpha)2+ (beta)2+2=\_\_\_\_\_.

- A. 0
- B. 2
- C. 3
- D. 6
- ANSWER: D
- 66. If alpha, beta, gamma are the roots of x3+2x+1=0, then the value (alpha)2+ (beta)2+2=\_\_\_\_\_.
  - A. 0
  - B. 2
  - C. 3
  - D. 6
- ANSWER: C
- 67. In an equation with rational coefficients, \_\_\_\_\_\_ roots must occur in conjugate pairs.A. irrational
  - B. imaginary
  - C. real
  - D. complex
  - ANSWER: A
- 68. In an equation with real coefficients, \_\_\_\_\_ roots must occur in conjugate pairs.A. irrational.
  - B. imaginary
  - C. real

D. complex ANSWER: D

69. A reciprocal equation of first class and odd degree has a root \_\_\_\_\_\_.

- A. 1
- B. 2
- C. -1
- D. -2

ANSWER: C

70. A reciprocal equation of second class and even degree has the roots \_\_\_\_\_\_.

- A. 1 and -1B. -1 and 2.
- C. 2 and -2
- D. -1 and 0
- ANSWER: A

71. Standard reciprocal equation is of the form \_\_\_\_\_\_.

- A. second class and odd degree
- B. second class and even degree
- C. first class and odd degree
- D. first class and even degree

ANSWER: D

72. Shifting operator is also called \_\_\_\_\_\_ operator.

- A. translation
- B. averaging
- C. differential
- D. unit

ANSWER: A

73. \_\_\_\_\_\_ errors are due to computational procedure.

- A. Inherent
- B. Round off
- C. Truncation
- D. Numerical

ANSWER: B

74. \_\_\_\_\_\_\_\_\_ errors are caused by using approximate formula in computation.

- A. Inherent
- B. Round off
- C. Truncation
- D. Numerical
- ANSWER: C

75. The number of \_\_\_\_\_\_ roots of f(x) = 0 does not exceed the number of changes of signin f(x).

- A. negative
- B. positive
- C. imaginary
- D. complex

- 76. As soon as a new value for a variable is found by iteration, it is used immediately in thefollowing equation. This method is called\_\_\_\_\_.
  - A. Gauss Seidel
  - B. Gauss Elimination
  - C. Gauss Jacobi
  - D. Gauss Jordan

ANSWER: A

- 77. The first difference of a constant is\_\_\_\_\_\_.
  - A. 0
  - **B.** 1
  - C. -1
  - D. -2

ANSWER: A

78. The nth difference of a polynomial of nth degree is\_\_\_\_\_.

- A. zero
- B. polynomial of (n-1)th degree
- C. constant
- D. polynomial in first degree

ANSWER: C

79. A second order differential equation can be solved by reducing it to a lower

\_\_\_\_\_equation.

- A. ordinary differential
- B. partial differential
- C. polynomial
- D. interpolation

ANSWER: A

80. The methods of second category are called \_\_\_\_\_ methods.

- A. direct
- B. indirect
- C. point wise
- D. step by step

ANSWER: C

81. In an ordinary differential equation the first category method is\_\_\_\_\_\_.

- A. Taylor method
- B. Euler method
- C. Modified Euler Method
- D. RungeKuttaMehtodANSWER: A
- 82. In which of the following methods proper choice of initial value is very important?
  - A. Newton Raphson Mehtod
  - B. Bisection Method
  - C. Iterative Method
  - D. Regula Falsi Method

ANSWER: A

- 83. An equation which expresses a relation between the independent and dependent variable iscalled \_\_\_\_\_\_ equation.
  - A. difference equation
  - B. ordinary differential equation
  - C. partial differential equation
  - D. quadratic equation

ANSWER: A

- 84. A function which satisfies the differential equations is called \_\_\_\_\_\_ of a differential equation.
  - A. solution
  - B. general solution
  - C. particular solution
  - D. complete solution

ANSWER: A

- 85. \_\_\_\_\_ of differential equation is a solution got form the general solution by givingparticular values to the arbitrary constant.
  - A. A solution
  - B. A general solution
  - C. A particular solution
  - D. A complete solution

ANSWER: C

- 86. For unequal intervals, we can use \_\_\_\_\_\_ to get the derivative value.
  - A. Newton Forward Interpolation Formula
  - B. Newton Backward Interpolation Formula
  - C. Lagrange's Interpolation Formula
  - D. Newton Difference Formula

ANSWER: D

- 87. To find the derivative for the start value(lies between) of the table \_\_\_\_\_\_ formula is used.
  - A. Newton Forward Interpolation Formula
  - B. Newton Backward Interpolation Formula
  - C. Newton Forward Difference Formula
  - D. Newton Backward Difference Formula

ANSWER: A

- 88. To find the derivative for the end value(lies between) of the table \_\_\_\_\_\_ formula is used.
  - A. Newton Forward Interpolation Formula
  - B. Newton Backward Interpolation Formula
  - C. Newton Forward Difference Formula
  - D. Newton Backward Difference Formula

ANSWER: B

- 89. To find the derivative for the end value(lies on) of the table \_\_\_\_\_\_ formula is used.
  - A. Newton Forward Interpolation Formula
  - B. Newton Backward Interpolation Formula
  - C. Newton Forward Difference Formula
  - D. Newton Backward Difference Formula

ANSWER: D

- 90. To find the derivative for the start value(lies on) of the table \_\_\_\_\_\_ formula is used.
  - A. Newton Forward Interpolation Formula
  - B. Interpolation Formula Newton Backward Interpolation Formula
  - C. Newton Forward Difference Formula
  - D. Newton Backward Difference Formula

ANSWER: C

91. If the value of derivative is required near the middle of the table we use \_\_\_\_\_\_ formula.

- A. Newton Forward Interpolation Formula
- B. Newton Forward Difference Formula
- C. Central Difference Formula
- D. Lanrange's Interpolation Formula

ANSWER: C

92. \_\_\_\_\_is derived from Newton's Cotes Formula.

- A. Trapezoidal Rule
- B. Simson's (1/3)rd Rule
- C. Simpson's(3/8)th Rule
- D. WeddlesRuleANSWER: A
- 93. Modification of \_\_\_\_\_\_ is called Romberg's method.
  - A. Trapezoidal Rule
  - B. Simson's (1/3)rd Rule
  - C. Simpson's(3/8)th Rule
  - D. WeddlesRuleANSWER: A

94. The degree of y(x) in Trapezoidal Rule is \_\_\_\_\_\_.

- A. 1
- B. 2
- C. 3
- D. 6

ANSWER: A

95. The degree of y(x) in Simpson's (1/3) rd rule is \_\_\_\_\_.

- A. 1
- B. 2
- C. 3
- D. 6

ANSWER: B

96. The degree of y(x) in Simpson's (3/8)th is\_\_\_\_\_.

- A. 1
- B. 2
- C. 3
- D. 6

ANSWER: C

97. In Simpson's (1/3) rd rule the number of intervals is \_\_\_\_\_\_.

- A. odd
- B. even

C. multiple of 3 D. multiple of 6 ANSWER: B

98. Interpolating polynomial is also known as\_\_\_\_\_\_.

- A. smoothing function
- B. interpolating function
- C. collocation polynomial
- D. interpolating formula

ANSWER: C

99. The method used to find the dominant Eigen value is \_\_\_\_\_\_.

- A. Gauss Method
- B. Newton's Method
- C. Euler's Method
- D. Power MethodANSWER: D

100. The nth differences of a polynomial of \_\_\_\_\_\_ degree are constants.

- A. n
- B. n+1
- C. n+2
- D. n+3

ANSWER: A

101. The (n+1)th polynomial of a degree n is \_\_\_\_\_\_.

- A. n
- B. n+1
- C. a constant
- D. zero
- ANSWER: D

102. Delta power two is called the \_\_\_\_\_order difference operator.

- A. first
- B. second
- C. third
- D. fourth
- ANSWER: B

103. Nabla power 3 is called the \_\_\_\_\_order difference operator.

- A. first
- B. second
- C. third
- D. fourth
- ANSWER: C

104. f(x-h) =\_\_\_\_\_.

- A. Ef(x)
- B. [E-1]f(x)
- C. [1/E]f(x)
- D. deltaf(x)

105. The power method for approximating Eigen value is \_\_\_\_\_ method. A. iterative B. point-wise C. direct D. indirect ANSWER: A 106. In Lagrange's interpolation formula, the value of L1(x1) = \_\_\_\_\_ A. 0 B. 1 C. 2 D. 3 ANSWER: A 107. Newton-Raphson method has a convergence. A. linear B. quadratic C. cubic D. bi quadratic ANSWER: B 108. If f(x) is continuous in (a, b) and if f(a) and f(b) are of opposite signs, then the equation f(x)=0 will have at least \_\_\_\_\_ between a and b. A. two real roots B. one real root C. three real roots D. four roots ANSWER: B 109. In the case of iteration method the convergence is . A. linear B. quadratic C. cubic D. bi quadratic ANSWER: A 110. In the case of Newton-Raphson method the error at any stage is proportional to\_\_\_\_\_. A. the error in the previous stage B. the square of the error in the previous stage C. the cubic of the error in the previous stage D. square root of the error in the previous stage ANSWER: B 111. The root of the equation e power x=4x lies between\_\_\_\_\_. A. (0, 1) B. (1, 2)

- C. (2, 3)
- D. (3, 4)
- ANSWER: C

112. A root of the equation x power x=100 lies between \_\_\_\_\_.

- A. (0, 1)
- B. (-1,-2)
- C. (-2, 3)
- D. (3, 4)
- ANSWER: D

113. Backward substitution method is applied in \_\_\_\_\_\_.

- A. Gauss Elimination Method
- B. Gauss Seidal Method
- C. Gauss Jacobi Method
- D. Newton's Raphson Method
- ANSWER: A
- 114. As soon as a new value for a variable is obtained by iteration, it is used immediately in thefollowing equation. This method is called \_\_\_\_\_\_.
  - A. Gauss Elimination Method
  - B. Gauss Seidal Method
  - C. Gauss Jacobi Method
  - D. Gauss Jacobi MethodANSWER: B

115. The algebraic sum of the errors in any difference column is \_\_\_\_\_\_.

- A. zero
- B. one
- C. constant
- D. same value
- ANSWER: A

116. Numerical differentiation can be used only when the difference of some order

- are\_\_\_\_\_
- A. equally spaced
- B. unequally spaced
- C. constant
- D. independent

ANSWER: C

117. Newton's divided difference formula is used only for \_\_\_\_\_\_ intervals.

- A. equal
- B. unequal
- C. open
- D. closed
- ANSWER: B
- 118. If a set of numerical values of a single valued integral function f(x), is applied to integralf(x), then the process is known as\_\_\_\_\_.
  - A. a numerical integration
  - B. quadrature
  - C. interpolation
  - D. a numerical differentiation

ANSWER: A

119. In deriving the trapezoidal formula for the curve y=f(x), each sub-interval is replaced

- byits\_\_\_\_\_
- A. straight line
- B. ellipse
- C. chord
- D. tangent line

ANSWER: C

120. Simpson's rule will give exact result if the entire curve y=f(x) is itself a \_\_\_\_\_

- A. straight line
- B. ellipse
- C. parabola
- D. tangent line

ANSWER: C

121. Taylor's series method will be very useful to give some initial starting values for powerfulmethods such as \_\_\_\_\_\_.

- A. Euler Method
- B. Modified Euler Method
- C. Newton Raphson Method
- D. RungeKuttaMethodANSWER: D

122. The modified Euler method is based on the average of \_\_\_\_\_\_.

- A. straight line
- B. ellipse
- C. chord
- D. points

ANSWER: D

123. Match the following: A.Newton Raphson 1.Integration B. Runge-kutta 2. Root finding C. Gauss-seidel 3. Ordinary Diferential Equations D. Simpson's Rule 4. Solution of system of Linear Equations Codes:ABCD

- A. 2341
- B. 3214
- C. 1423
- D. 1243
- ANSWER: A

124. In numerical integration, to get better result, we select n as\_\_\_\_\_.

- A. even
- B. odd
- C. 1,2,3,4,5,6.....
- D. large as possible

ANSWER: D

125. In divided difference formula, the value of any difference is \_\_\_\_\_\_of the order of theirarguments.

- A. independent
- B. dependent
- C. inverse

D. transpose ANSWER: A

126. The word Eigen value is derived from a German word Eigen meaning \_\_\_\_\_.

- A. characteristic
- B. substitute
- C. dominant
- D. least

ANSWER: A

127. For a transition matrix the dominant eigen value is always \_\_\_\_\_.

- A. 0
- B. 1
- C. 2
- D. 3

ANSWER: B

128. The divided difference formula is \_\_\_\_\_\_ in all their arguments.

- A. asymmetrical
- B. symmetrical
- C. inverse

D. transpose

ANSWER: B

129. Which of the following states If f(x) is three times differentiable and f', f"are not zero for asolution of f(x) = 0, then x0 sufficiently close to s?

- A. Newton's method of first order
- B. Newton's method of second order
- C. Newton's method of third order
- D. Newton's divided difference method

ANSWER: B

130. In Newton-cotes formula, if f(x) is interpolated at equally spaced nodes by a polynomial ofdegree two then it represents\_\_\_\_\_.

- A. Trapezoidal rule
- B. Simpson's one-third rule
- C. Simpson's three-eigth rule

D. Euler's rule

ANSWER: B

- 131. In Newton-cotes formula, if f(x) is interpolated at equally spaced nodes by a polynomial ofdegree three then its represents\_\_\_\_\_. A. Trapezoidal rule.
  - B. Simpson's one-third rule
  - C. Simpson's three-eigth rule
  - D. Euler's rule

ANSWER: C

132. Which of the following is true?

- A. Delta=E-1
- B. Nabla=Delta
- C. Delta=Nable+1

D. Delta=Nabla-1 ANSWER: A

133. Let h be the finite difference, then forward difference operator is defined by \_\_\_\_\_.

- A. f(x)=f(x+h)-f(x)
- B. f(x)=f(x-h)-f(x)
- C. f(x)=f(x\*h)
- D. f(x)=f(x)

ANSWER: A

134. There is at most one polynomial of degree less than or equal to n\_\_\_\_\_.

- A. which interpolates f(x) at (n+1) distinct points x0,x1,...xn
- B. which interpolates f(x) at (n-1) distinct points x0,x1,...xn-1
- C. which interpolates f(x) at n distinct points x0,x1,...xn-2
- D. which interpolates f(x) at (n-1) distinct points x0,x1,...xn-3

ANSWER: A

135. A differential equation is said to be linear if\_\_\_\_\_.

- A. the dependent variable and its differential co-efficient occur in the second degree
- B. the dependent variable occurs in the first degree
- C. the dependent variable and its differential co-efficient occur only in the first degree

D. the independent variable occurs in the first degree

ANSWER: C

- 136. The solution of a differential equation which contains number of arbitrary constants equal to the order of the differential equation is called the \_\_\_\_\_.
  - A. elementary solution
  - B. complementary function
  - C. particular solution
  - D. general solution

ANSWER: D

137. In the general solution of a differential equation, the arbitrary constants are \_\_\_\_\_.

- A. dependent
- B. independent
- C. both dependent and independent
- D. neither dependent nor independent

ANSWER: B

138. The simplest method in finding the approximate solutions to the first order equations

- is\_\_\_\_\_.
- A. Euler's method
- B. Modified Euler's Method
- C. Runge-Kutta method
- D. Taylor's Method

ANSWER: A

- 139. If a polynomial of degree n has more than n zeros, then the polynomial is \_\_\_\_\_.A. oscillatory
  - B. zero everywhere
  - C. quadratic

D. not defined ANSWER: B

140. To find the negative root of f(x)=0, we should find the corresponding positive root of and change the sign.

- A. f(x)=0
- B. f(x)=y
- C. f(-x)=y
- D. f(-x)=0
- ANSWER: C

141. To find the real root of a polynomial equation we use \_\_\_\_\_\_ method.

- A. Bisection
- B. Newton's
- C. Euler's
- D. Horner's
- ANSWER: D

142. \_\_\_\_\_method is faster than bi-section method.

- A. Gauss-elimination
- B. Newton's
- C. Horner's
- D. Regula-falsi

ANSWER: D

143. \_\_\_\_\_ method is slower than Newton's Raphson Method.

- A. Gauss-elimination
- B. Newton's
- C. Horner's
- D. Regula-falsi

ANSWER: D

144. The most popular Runge-Kutta method is \_\_\_\_\_\_.

- A. First order Runge-Kutta method
- B. Second order Runge-Kutta method
- C. Third order Runge-Kutta method
- D. Fourth order Runge-Kutta method

ANSWER: D

145. The convergence rate of the \_\_\_\_\_\_method is poor, when two largest eigen values arenearly equal in magnitude.

- A. Power
- B. Newton's
- C. Euler's
- D. Bolzano's

ANSWER: A

146. \_\_\_\_\_are best suited for finding a set of interpolation polynomials for increasing values of r.

- A. Newton forward and backward interpolation formula
- B. Newton and Backward difference formula

- C. Lagrange's interpolation formula
- D. Taylor's formula

ANSWER: A

147. The process of numerical integration of a function of a single variable is called\_\_\_\_\_.

- A. Trapezoidal Rule
- B. Simpson's Rule
- C. Cubature
- D. Quadrature
- ANSWER: D

148. The process of numerical integration of a function of a two variable is called \_\_\_\_\_.

- A. Trapezoidal Rule
- B. Simpson'sRule
- C. Cubature
- D. Quadrature

ANSWER: C

149. Simpson's rule for evaluation of integral gives better result if f(x) = 0 represents\_\_\_\_\_.

- A. a circle
- B. a parabola
- C. an ellipse
- D. a hyperbola

ANSWER: B

150. The product and sum of the roots of the equation x power 5=2 are \_\_\_\_\_ and \_\_\_\_\_.A.

- (1,2)
- B. (5,2)
- C. (2,5)
- D. ( 2,0)
- ANSWER: D